

Explore the opportunity of applying Generative AI in High Energy Physics

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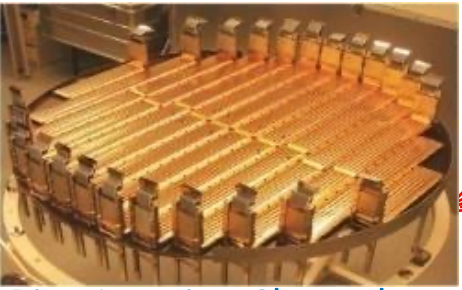
Oct 30, 2024

AMS (A TeV precision, multipurpose magnetic spectrometer)

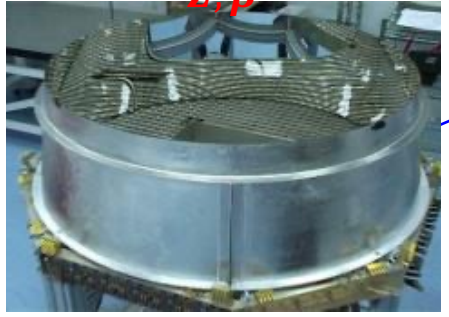
Transition Radiation Detector (TRD)
Identify p^\pm/e^\pm



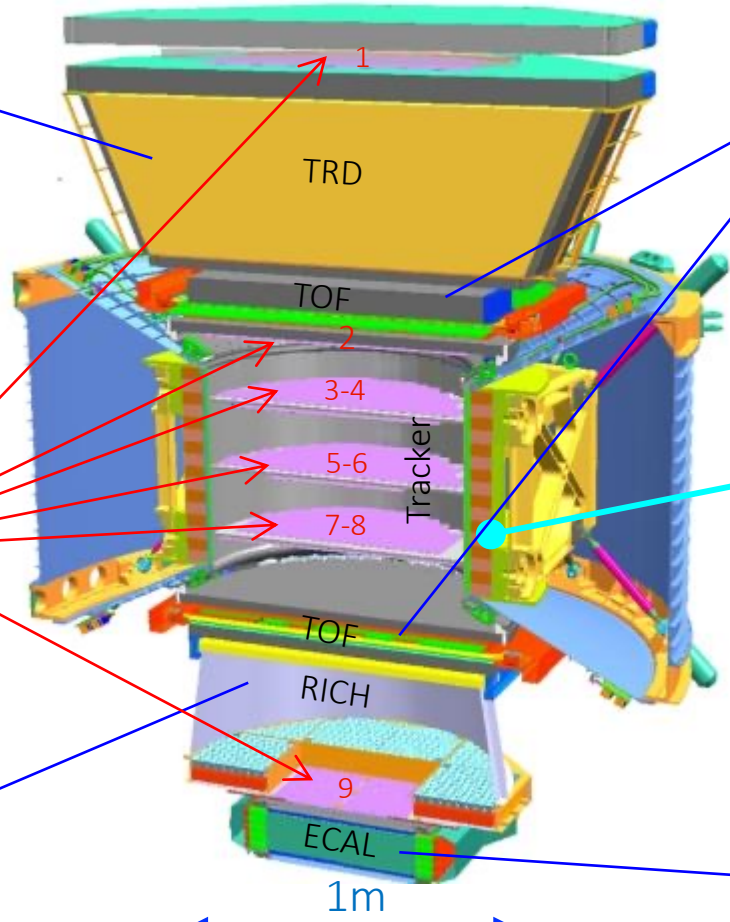
Silicon Tracker (Tracker)
 Z, P



Ring Imaging Cherenkov (RICH)
 Z, β



The charge (Z) and energy (E) or rigidity ($R \equiv P/Z$) are measurement independently by several detectors

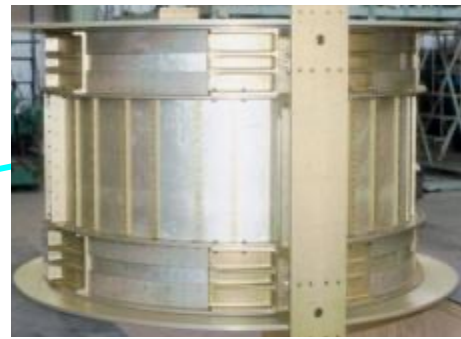


Volume: 5m x 4m x 3m
Weight: 7.5 tons

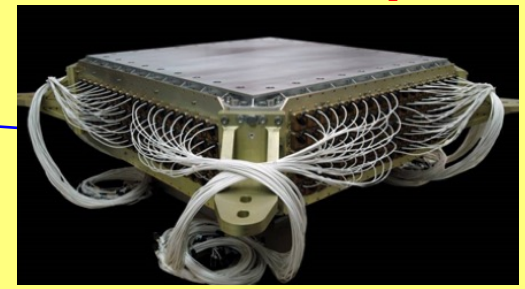
Time of Flight (TOF)
 Z, β



Magnet (~0.14 Tesla)
 $\pm Z$

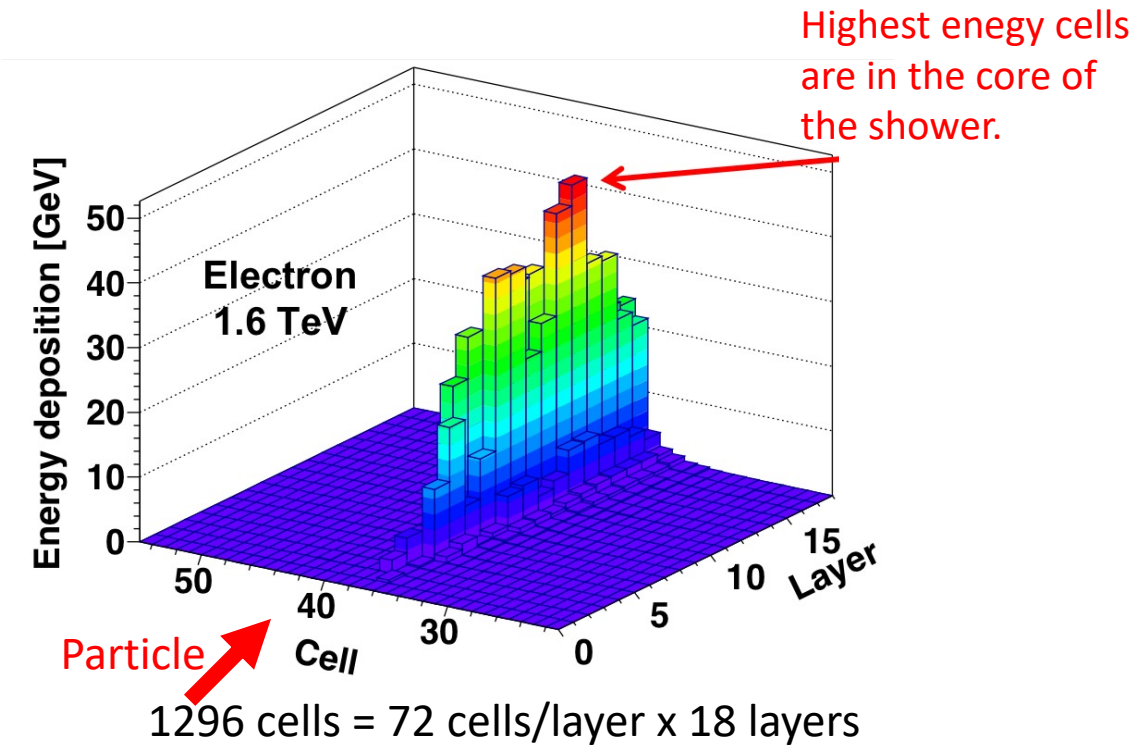
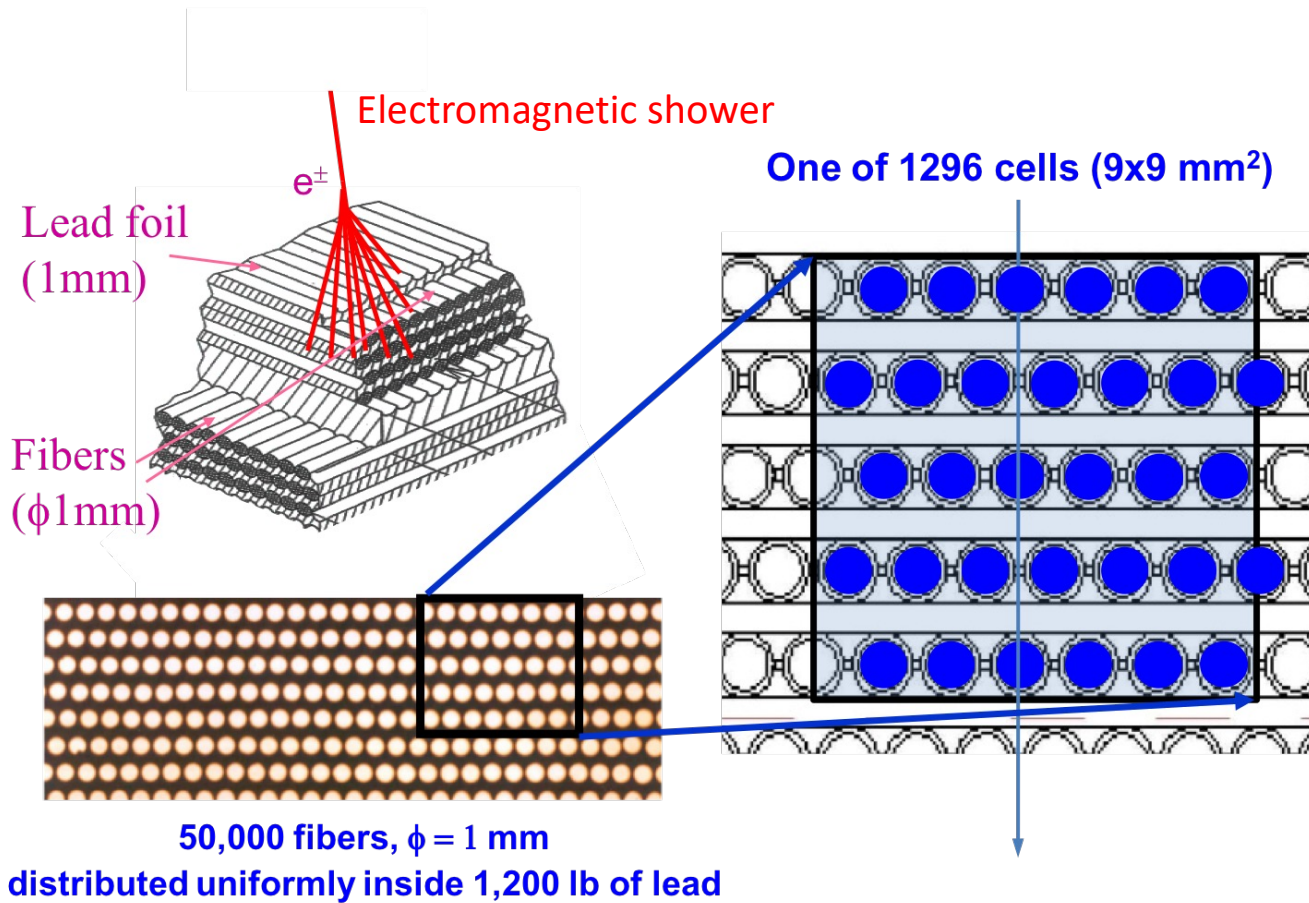


Electromagnetic Calorimeter (ECAL)
 E of e^\pm and Identify p^\pm/e^\pm



- Absolute Charge $|Z|$
- Tracker & TOF
- Energy of e^\pm
- ECAL
- Charge-Sign
- Rigidity R
- Tracker with Magnet
- Velocity $\beta = v/c$
- TOF & RICH
- p^\pm/e^\pm identification
- TRD & ECAL

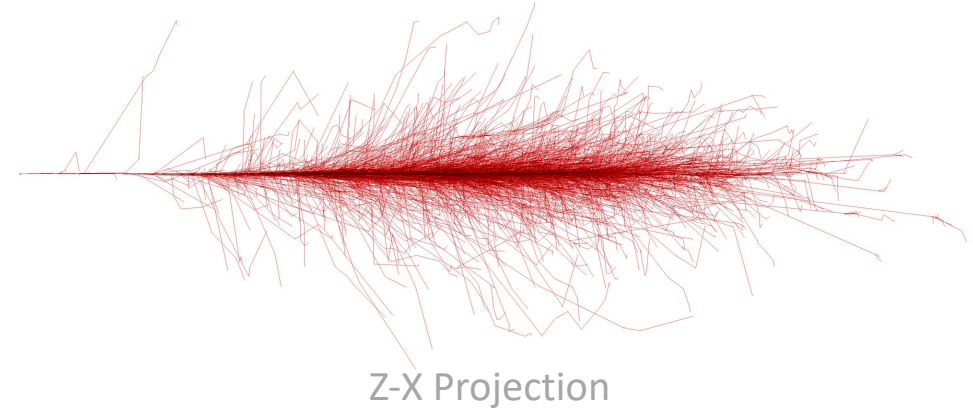
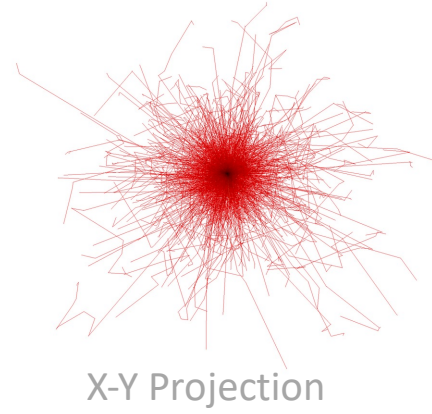
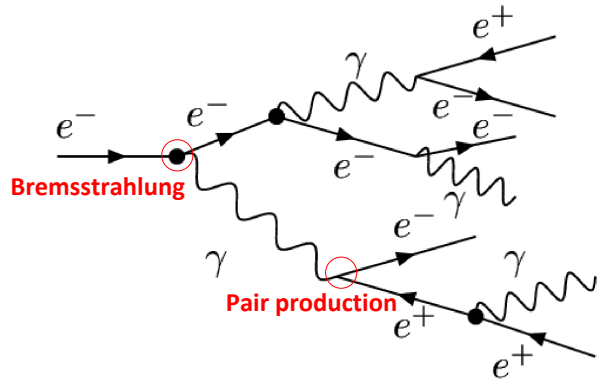
AMS Electromagnetic Calorimeter (ECAL)



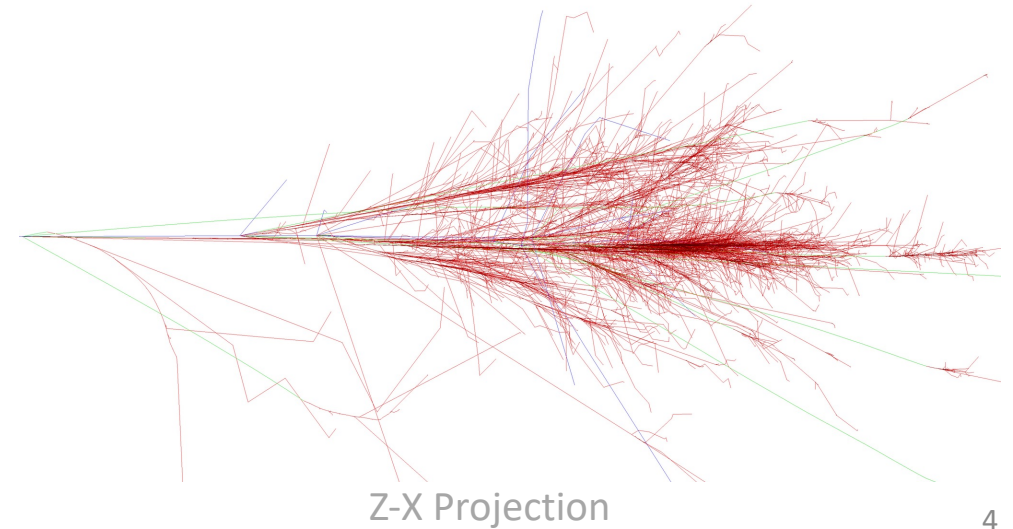
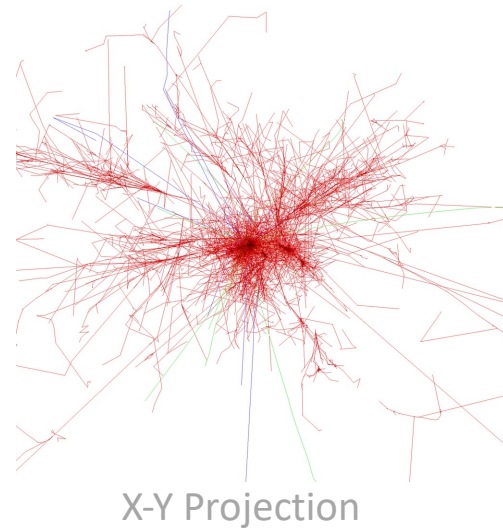
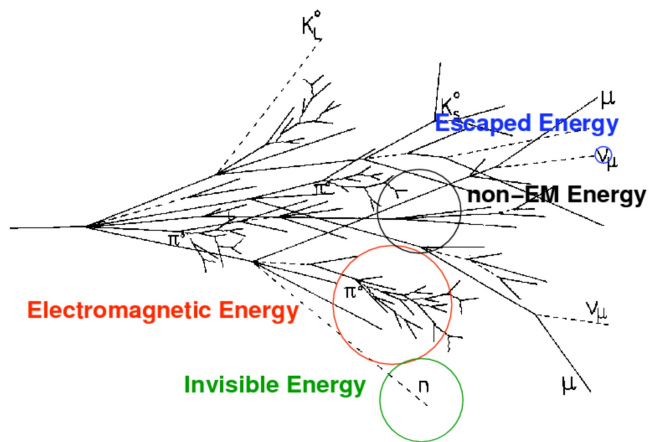
Direction Projection of Layers (10 in Z-Y, 8 in Z-X)

Y	Y	X	X	Y	Y	X	X	Y	Y	X	X	Y	Y	X	X	Y	Y
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

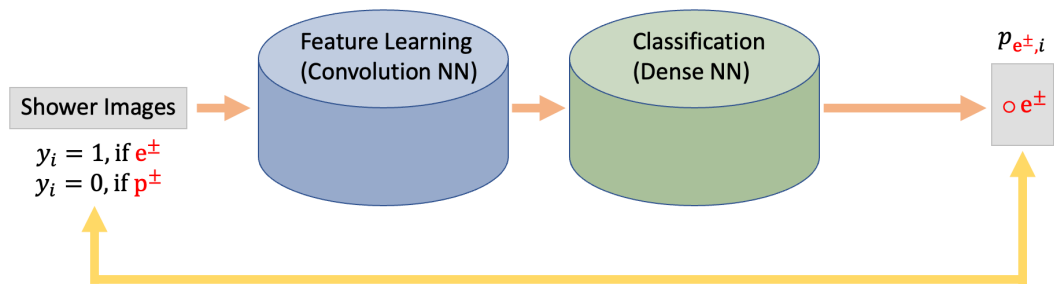
Electromagnetic (EM) Shower (e^\pm)



Hadron Shower (p^\pm)



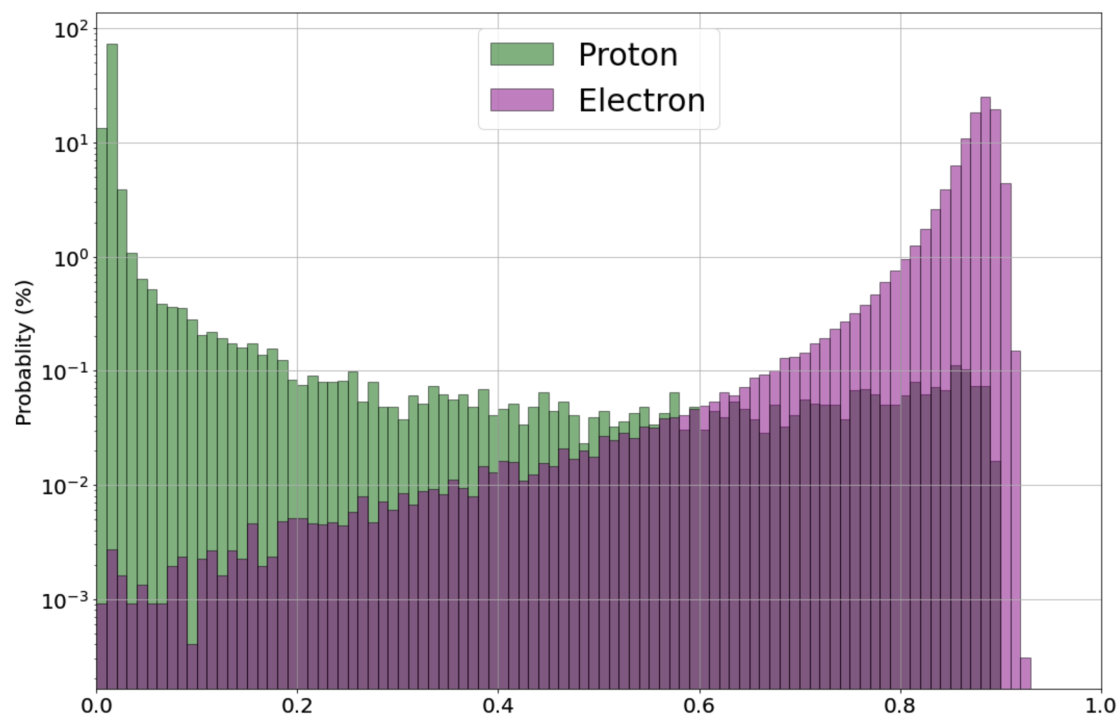
Classification



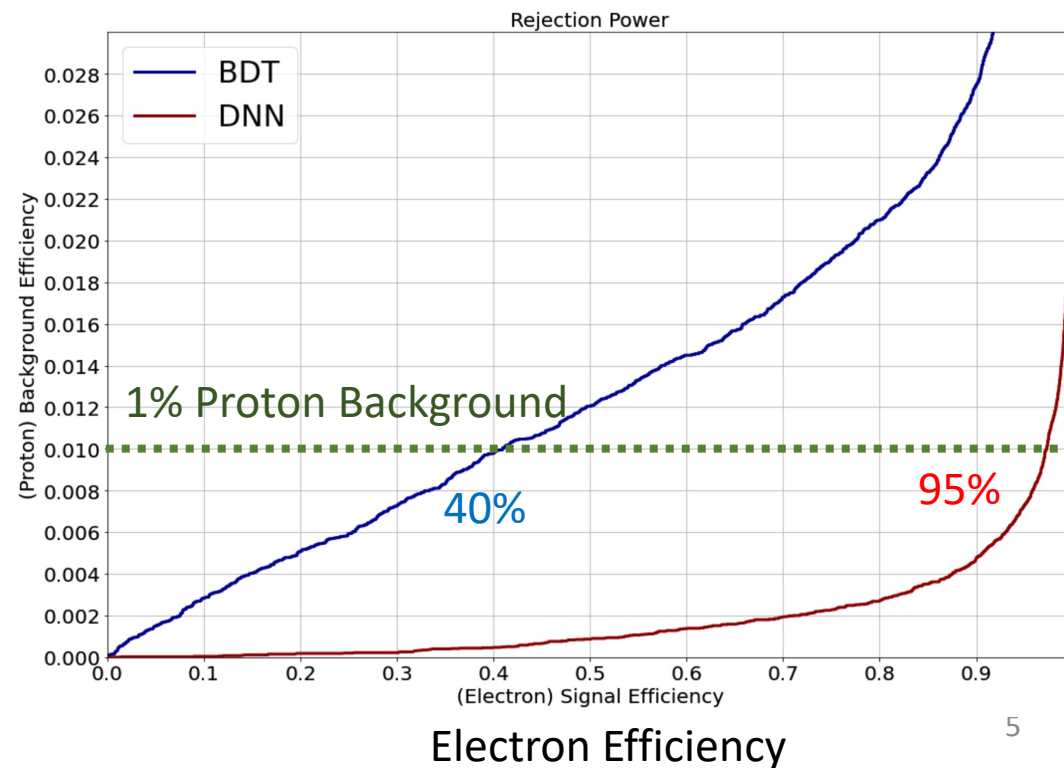
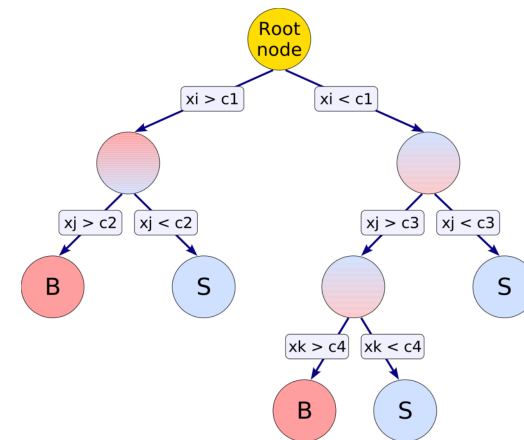
Loss function: Binary Cross Entropy

$$\mathcal{L} = -\frac{1}{N} \sum_{i=1}^N [y_i \cdot \ln(p_{e^{\pm}, i}) + (1 - y_i) \cdot \ln(1 - p_{e^{\pm}, i})]$$

Deep Neural Network (DNN)

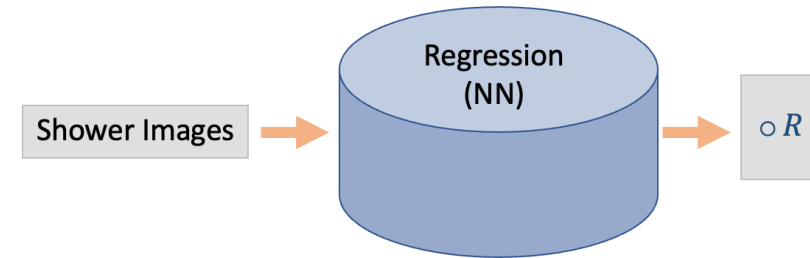


Boost Decision Tree (BDT)



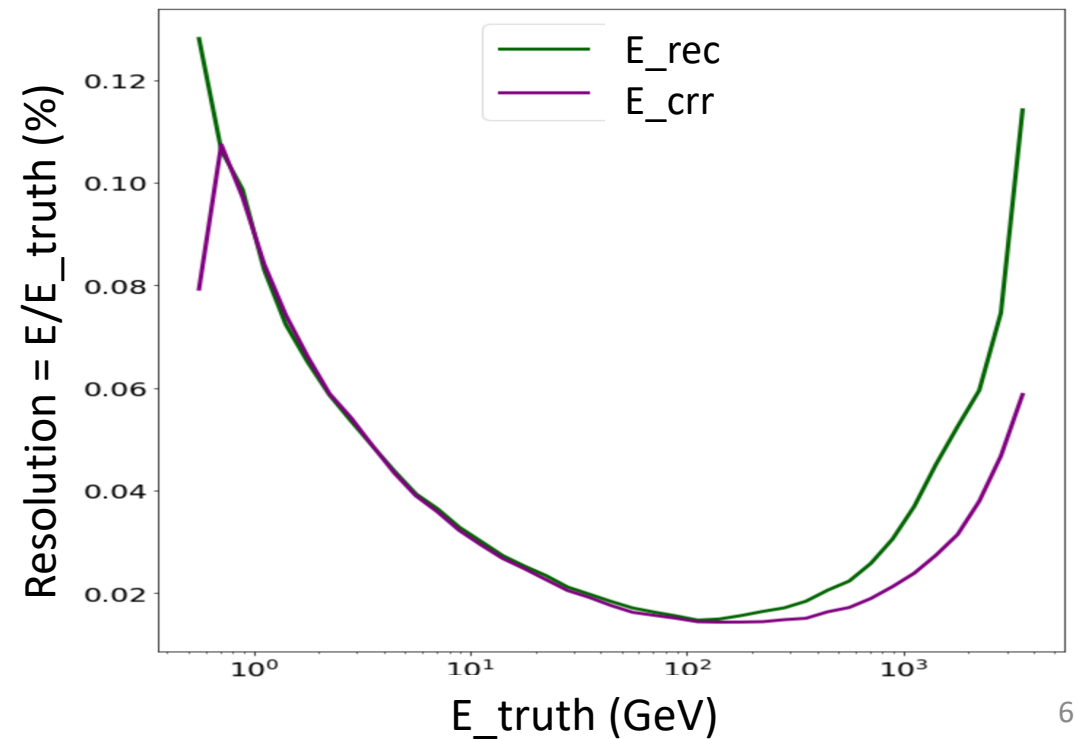
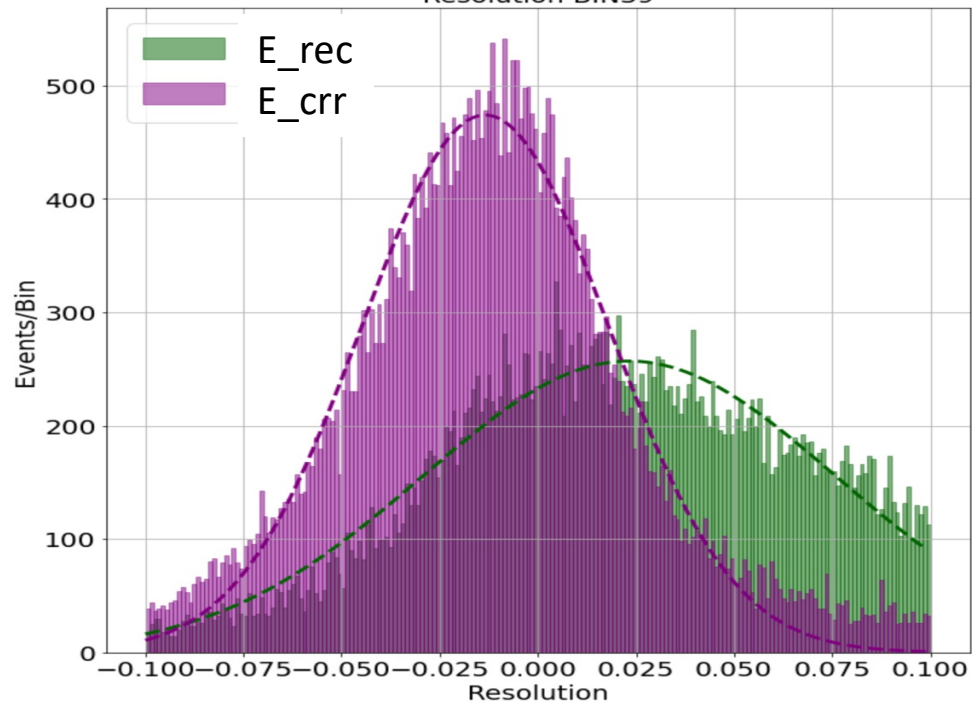
Electron Energy Correction (Regression)

- Input Variables: 18x72 ECAL cell energies
- Output Variable: $R = ((E_{\text{rec}} / E_{\text{truth}}) - 1)$
- Corrected Energy: $E_{\text{crr}} = E_{\text{rec}} / (1 + R)$



Preliminary Results (1584-2000 GeV)

Resolution BIN39



Shower Simulation (Generator)

Physical Simulation

- Simulate the passage of particles through materials
- Monte Carlo Method: Geant4 toolkit
- Hardware Resources: CPUs

DL-based Fast Simulation

- 100 to 1000 faster than the physical simulation
- DL Algorithms:
 - Generative Adversarial Networks (GANs)
 - Diffusion Model
 - ...
- Hardware Resources: GPUs

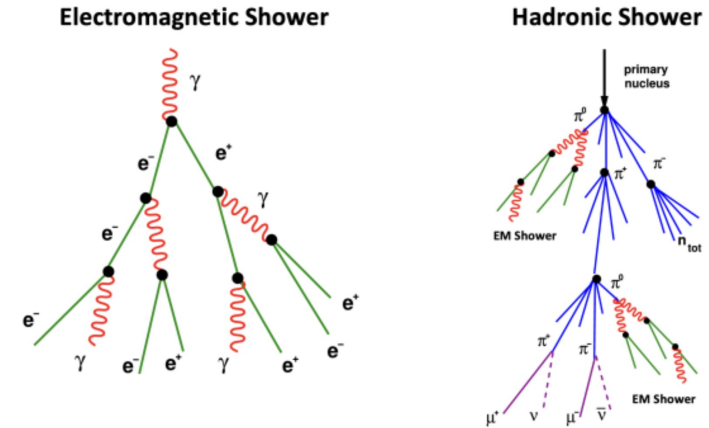
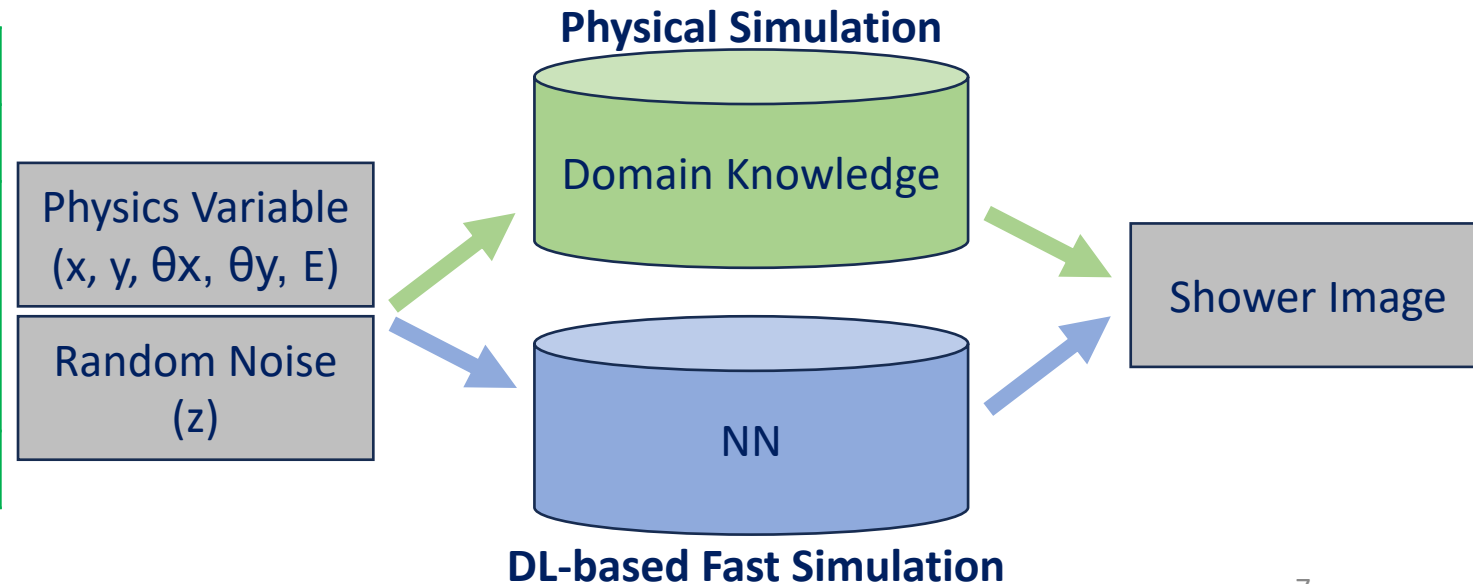


Figure 1. Electromagnetic shower and hadronic shower.



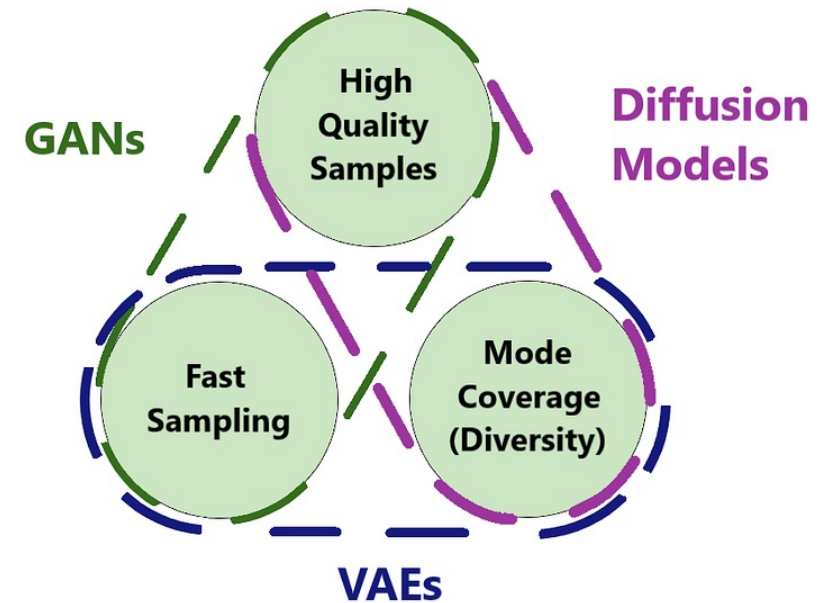
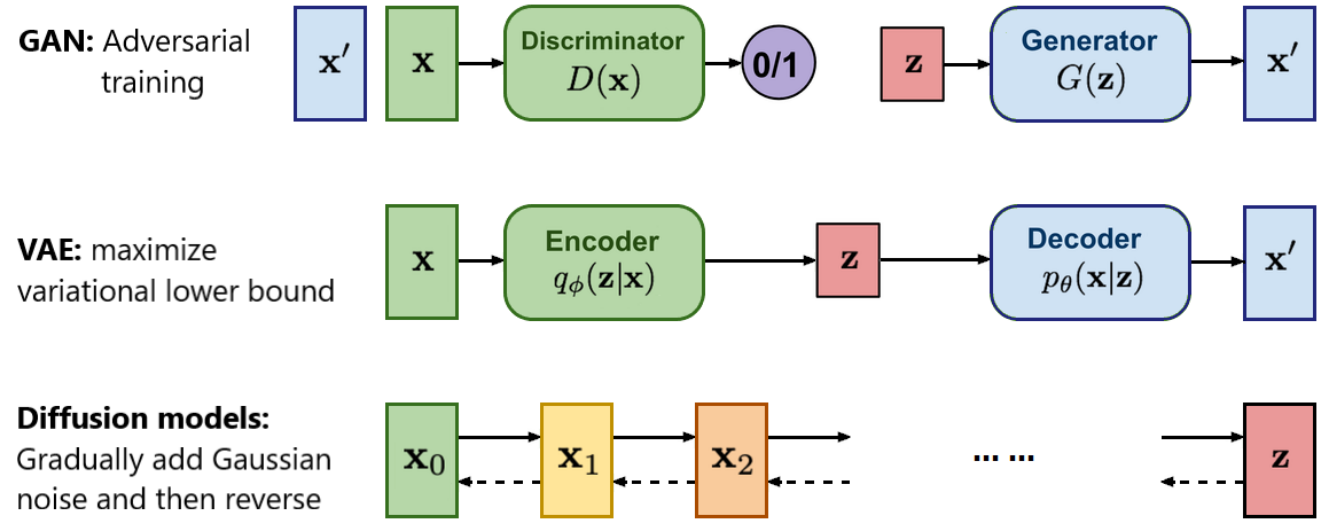
Generator

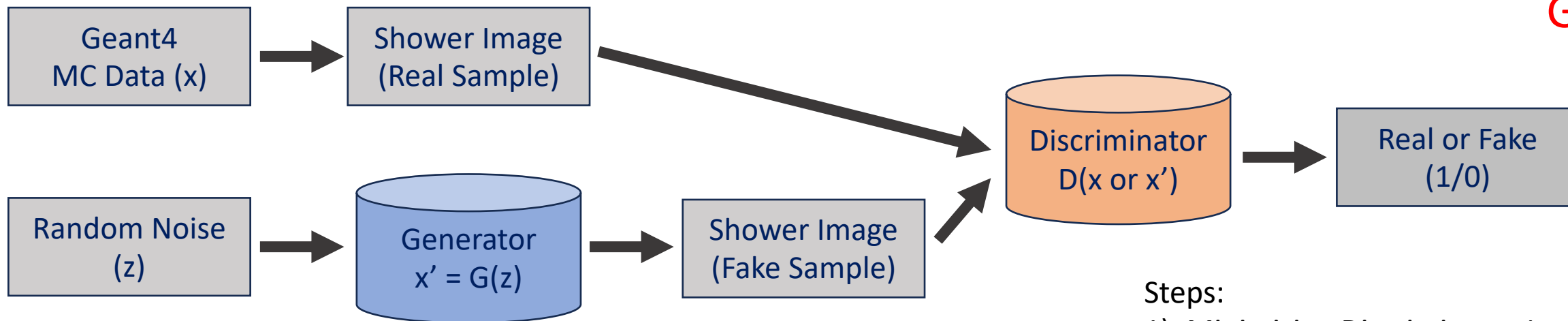
<https://pub.towardsai.net/diffusion-models-vs-gans-vs-vaes-comparison-of-deep-generative-models-67ab93e0d9ae>

GANs [1, 2] learn to generate new data similar to a training dataset. It consists of two neural networks, a generator, and a discriminator, that play a two-player game. The generator takes in random values sampled from a normal distribution and produces a synthetic sample, while the discriminator tries to distinguish between the real and generated sample. The generator is trained to produce realistic output that can fool the discriminator, while the discriminator is trained to correctly distinguish between the real and generated data. The top row of Figure 1 shows the scheme of its work.

VAEs [3, 4] consist of an encoder and a decoder. The encoder maps high-dimensional input data into a low-dimensional representation, while the decoder attempts to reconstruct the original high-dimensional input data by mapping this representation back to its original form. The encoder outputs the normal distribution of the latent code as a low-dimensional representation by predicting the mean and standard deviation vectors. The middle row of Figure 1 demonstrates its work.

Diffusion models [5, 6] consist of forward diffusion and reverse diffusion processes. Forward diffusion is a Markov chain that gradually adds noise to input data until white noise is obtained. It is not a learnable process and typically takes 1000 steps. The reverse diffusion process aims to reverse the forward process step by step removing the noise to recover the original data. The reverse diffusion process is implemented using a trainable neural network. The bottom row of Figure 1 shows that.

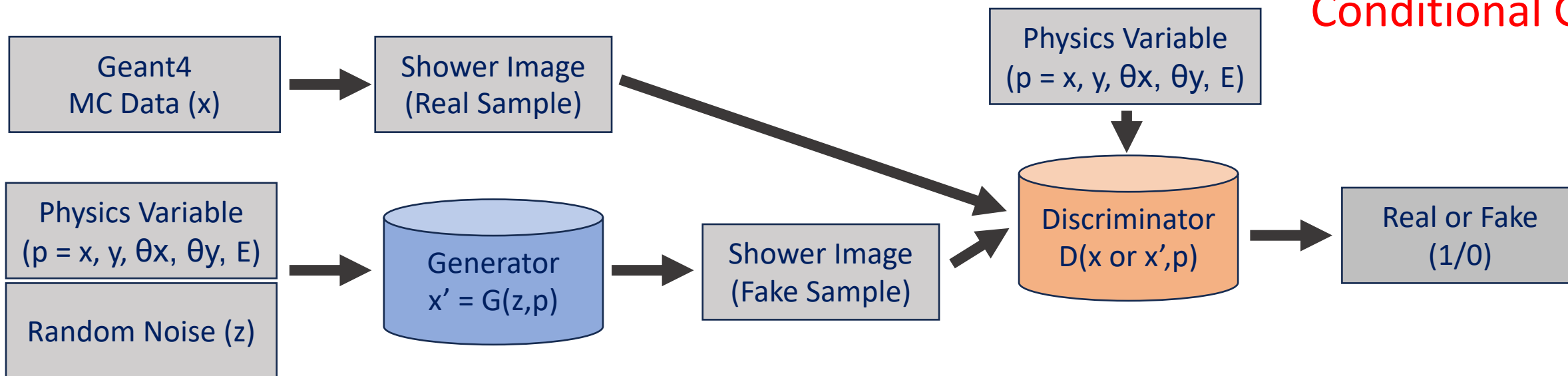




Discriminator Loss = $-\text{mean}\{\log[D(x)] + \log[1 - D(x')]\} = -\{\log[D(x)] + \log[1 - D(G(z))]\}$

Generator Loss = $-\text{mean}\{\log[D(G(z))]\}$

Conditional GAN



Discriminator Loss = $-\{\log[D(x, p)] + \log[1 - D(G(z, p), p)]\}$

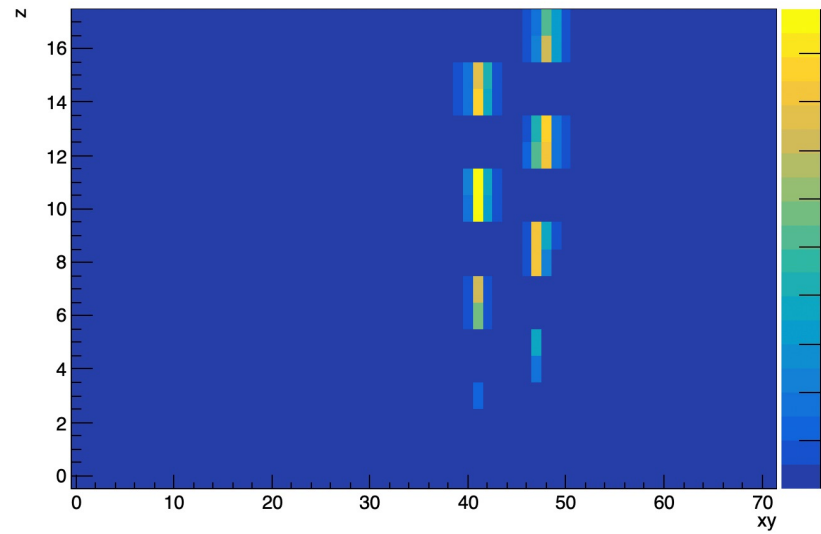
Generator Loss = $-\log[D(G(z, p))] + \lambda * \text{MSR}(G(z, p), x)$

$\text{MSR}(G(z, p), x) = \text{mean}\{(G(z, p) - x)^2\}$

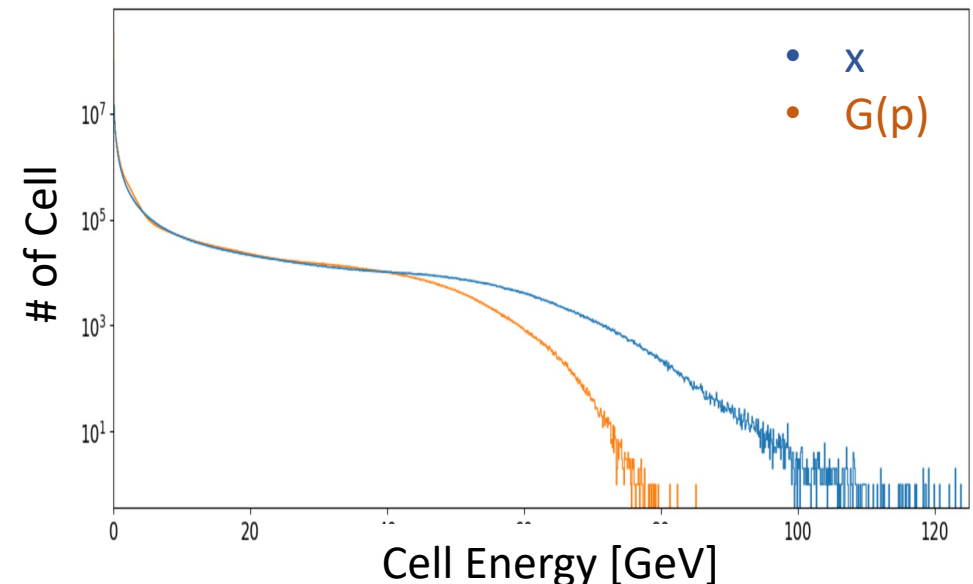
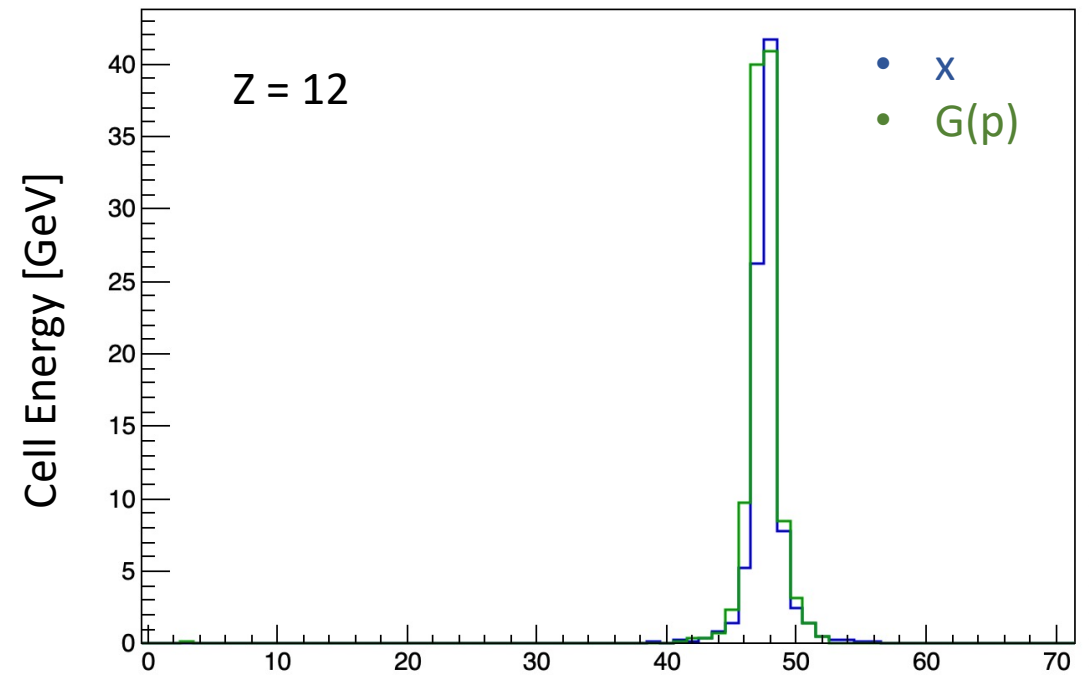
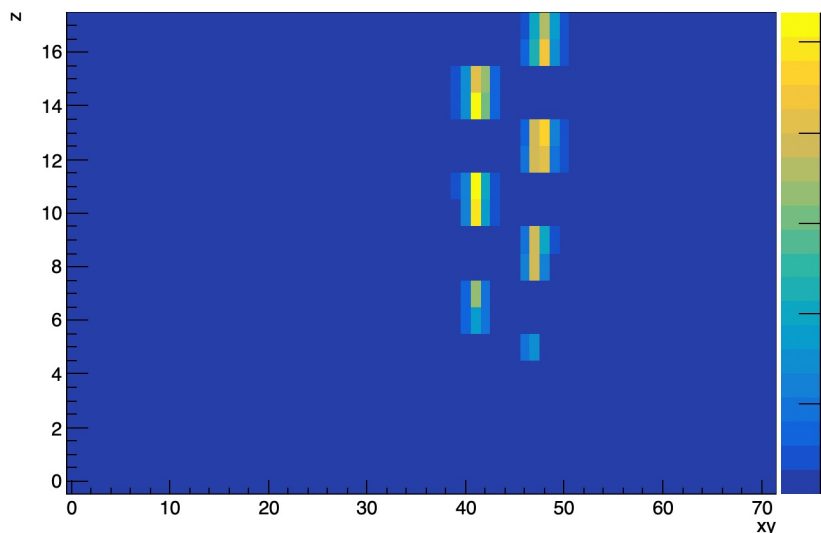
Step 1:

$$\text{Generator Loss} = \text{MSR}(G(p), x)$$

Real image (Geant4 MC) $E = 1466$ GeV



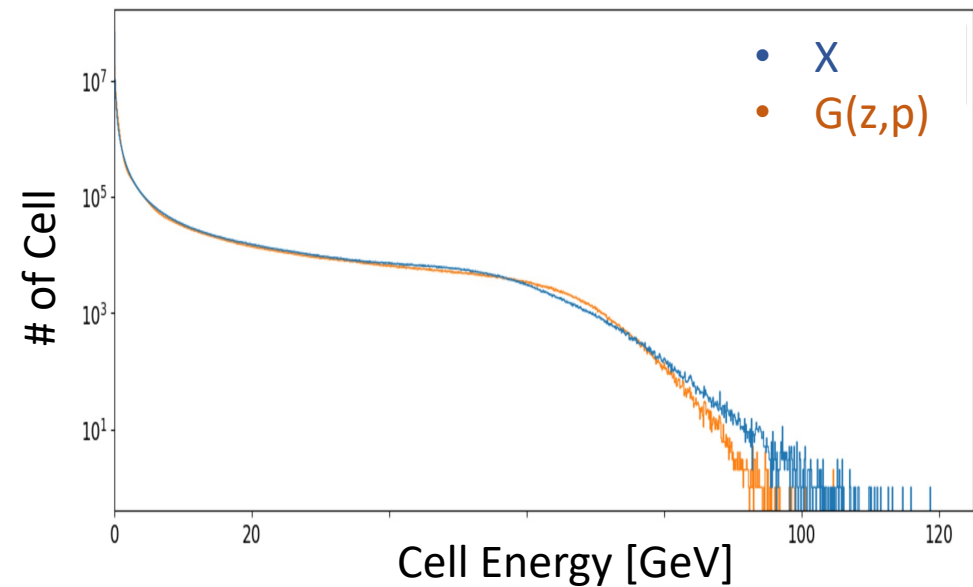
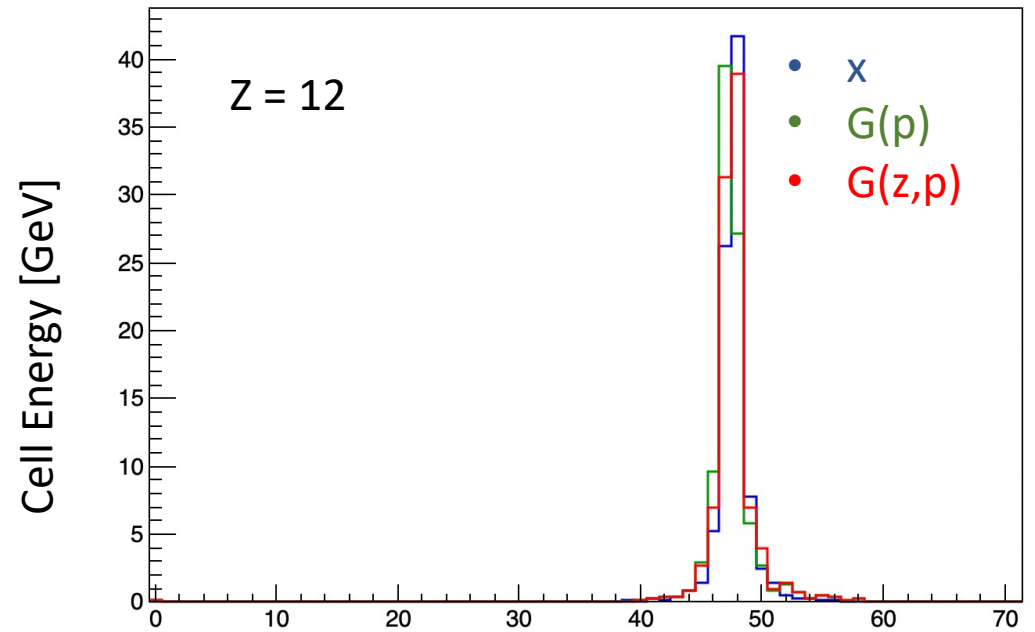
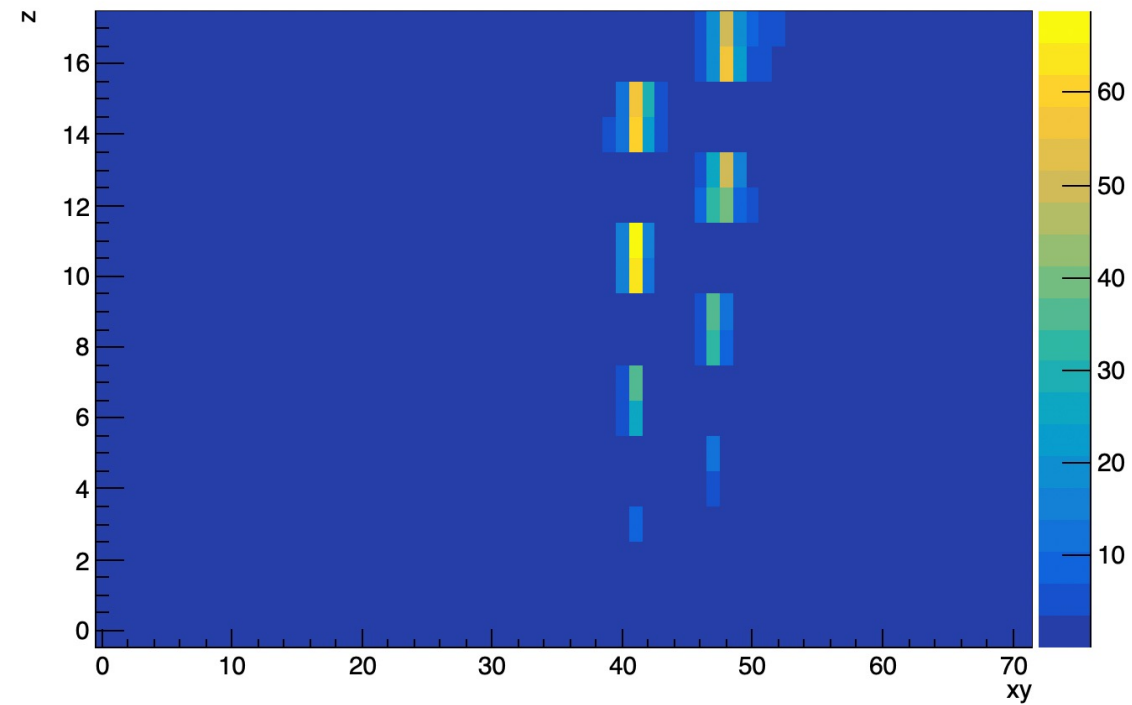
Reconstruction image $G(p)$



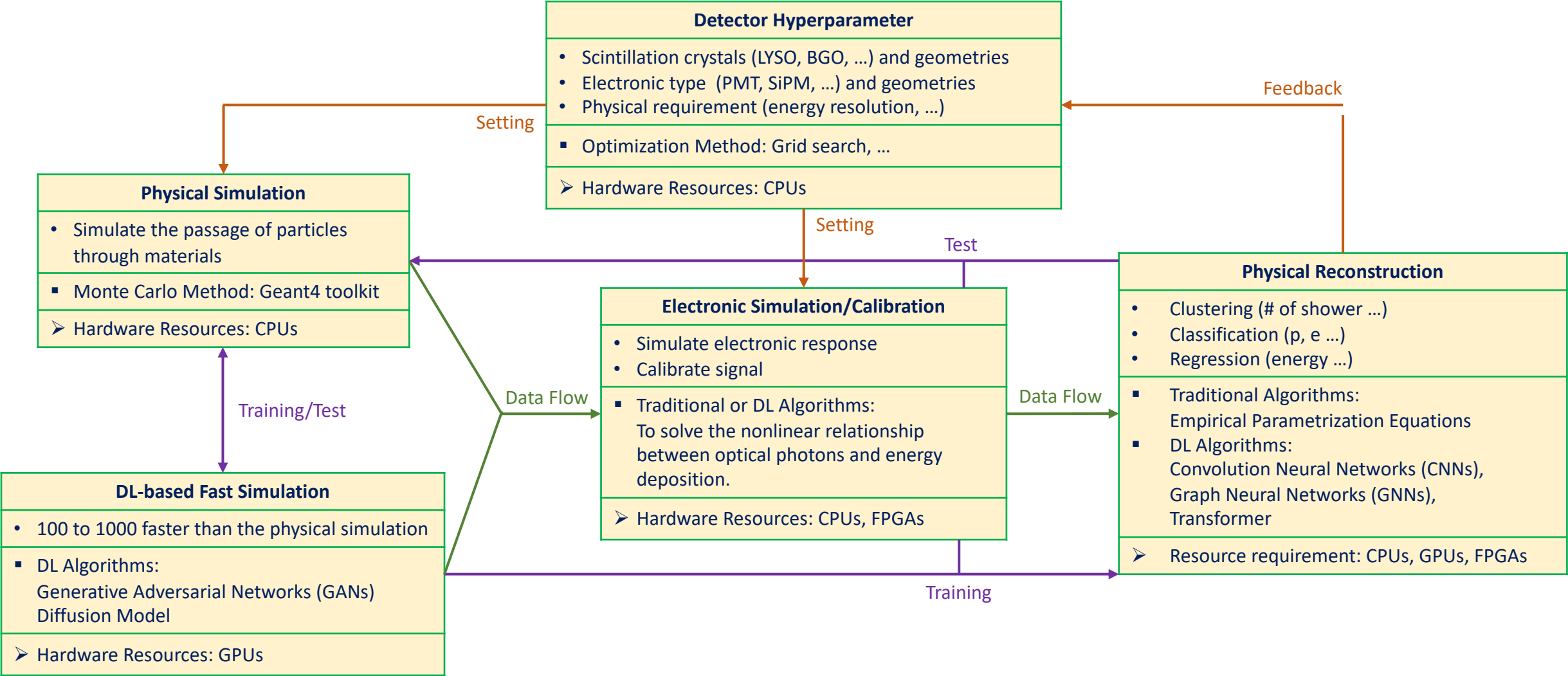
Step 2:

$$\text{Discriminator Loss} = -\{ \log[D(x,p)] + \log[1 - D(G(z,p),p)] \}$$
$$\text{Generator Loss} = -\log[D(G(z,p))] + \lambda * \text{MSR}(G(z,p), x)$$

Simulation image $G(z,p)$ $E = 1466$ GeV



Calorimeter Design Tool in High Energy Physics



Computing Resource

[Remote Terminal]

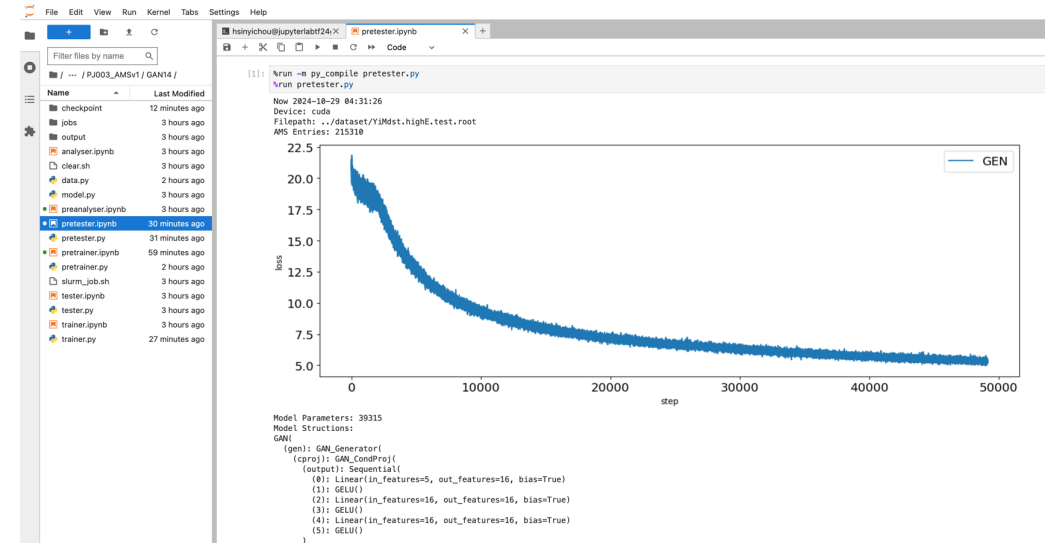
slurm-ui-asiop.twgrid.org

slurm-ui03.twgrid.org

...

```
1 import torch
2 import torch.nn as nn
3 import torch.nn.functional as F
4
5 device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
6
7 class PixelShuffle1D(torch.nn.Module):
8     def __init__(self, upscale_factor):
9         super(PixelShuffle1D, self).__init__()
10        self.upscale_factor = upscale_factor
11
12    def forward(self, x):
13        batch_size, channels, length = x.size()
14
15        # Check if channels can be evenly divided by upscale_factor
16        if channels % self.upscale_factor != 0:
17            raise ValueError(f"Channels must be divisible by {self.upscale_factor}")
18
19        # Perform pixel shuffle
20        channels //= self.upscale_factor
21        x = x.view(batch_size, channels, self.upscale_factor, length)
22        x = x.permute(0, 1, 3, 2) # Rearrange dimensions
23        x = x.contiguous().view(batch_size, channels, length * self.upscale_factor)
24        return x
25
26 class PixelUnshuffle1D(torch.nn.Module):
27     def __init__(self, downscale_factor):
28         super(PixelUnshuffle1D, self).__init__()
29        self.downscale_factor = downscale_factor
30
31    def forward(self, x):
32        batch_size, channels, length = x.size()
33
34        # Check if the length is divisible by downscale_factor
35        if length % self.downscale_factor != 0:
36            raise ValueError(f"Length must be divisible by {self.downscale_factor}")
37
38        # Perform pixel unshuffle
39        out_channels = channels * self.downscale_factor
40        out_length = length // self.downscale_factor
41
42        # Reshape and permute the tensor
43        x = x.view(batch_size, channels, out_length, self.downscale_factor)
44        x = x.permute(0, 1, 3, 2) # Rearrange dimensions
45        x = x.contiguous().view(batch_size, out_channels, out_length)
46        return x
47
```

[DiCOS Apps]
Jupyter Lab GPU



[Slurm]
CPUs, GPUs A100, V100, ...

```
(ml) [hsinyichou@slurm-ui-asiop GAN14]$ squeue | grep a100
230030      a100  HMC0034  twchiu PD      0:00      1 (Nodes required for
231049      a100  HMC0036  twchiu PD      0:00      1 (Priority)
232091      a100  HMC0035  twchiu PD      0:00      1 (Priority)
232098      a100  HMC0033  twchiu PD      0:00      1 (Priority)
233667      a100  handbook noke0081 R      18:00      1 hp-teslaa03
232635      a100  handbook noke0081 R      1:01:53      1 hp-teslaa03
194890 a100_long urg_seja rc PD      0:00      1 (Dependency)
194888 a100_long urg_seja rc PD      0:00      1 (Dependency)
194887 a100_long urg_seja rc PD      0:00      1 (Dependency)
194886 a100_long urg_seja rc PD      0:00      1 (Dependency)
176131 a100_long urg_seja rc PD      0:00      1 (Dependency)
176130 a100_long urg_seja rc PD      0:00      1 (Dependency)
176129 a100_long urg_seja rc PD      0:00      1 (Dependency) 13
176128 a100_long urg_seja rc PD      0:00      1 (Dependency)
176127 a100_long urg_seja rc PD      0:00      1 (Dependency)
```